## THE GEOMETRY OF VECTOR BUNDLES AND AN INTRODUCTION TO GAUGE THEORY LECTURE 15

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## Connections on Vector Bundles I

There are three points of view of connections:

- (1) A connection is a device for computing derivatives of sections of a vector bundle.
- (2) A connection is a device for decomposing tangent spaces to points in E into
  - Vertical directions (along fibers of of  $E \to B$ ).
  - Horizontal directions ("parallel" to tangent directions to B).
- (3) A connection is a device for comparing fibers of E at different points  $b_1$  and  $b_2$  by "parallel transport along a curve".

Before going on, we give a brief overiew of how these points of view are related. We start with (1), that is, the problem of differentiating sections.

Given  $f \in C^{\infty}(B, \mathbb{R})$ , we get df, a global 1-form on B. That is,

$$d: C^{\infty}(B, \mathbb{R}) \to \Omega^1(B) = \Omega^0(B, T^*B)$$

such that  $d: f \mapsto df$ . Recall that  $df_b: T_b B \to \mathbb{R}$  is given by  $df_b(X_b) = X(f)(b) = \frac{d}{dt} f(\gamma(t)) \Big|_{t=0}$  if  $X_b \sim [\gamma(t)]$ .

Now we can do the similar thing for  $f: B \to \mathbb{R}^n$ :

Given  $X_b \sim [\gamma(t)]$ ,  $\frac{d}{dt}f(\gamma(t))\Big|_{t=0} = (df_{1_b}(X_b), \cdots, df_{n_b}(X_b))$ . So  $df = (df_1, \cdots, df_n)$  measures variation of f along  $\gamma(t)$ , that is,  $df \in \Omega^0(B, T^*B \otimes \underline{\mathbb{R}}^n)$ . Thus we get

$$d:C^{\infty}(B,\mathbb{R}^n)\to\Omega^0(B,T^*B\otimes\underline{\mathbb{R}^n})=\Omega^1(B,\underline{\mathbb{R}^n}).$$

What about for  $s: B \to E$ , that is,  $s \in \Omega^0(B, E)$ ?

How do we make sense of  $\frac{d}{dt}s(\gamma(t))\Big|_{t=0}$ ?

Problem:

$$\left. \begin{array}{l} s(\gamma(t)) \in E_{\gamma(t)} \\ s(\gamma(0)) \in E_{\gamma(0)} \end{array} \right\} \quad \text{ cannot be identified.}$$

Therefore we cannot evaluate  $s(\gamma(t)) - s(\gamma(0))$ .

If we had a way of "lining up" / "identifying" all  $E_{\gamma(t)}$  along  $\gamma(t)$  (to  $E_{\gamma(0)}$ ), then we could measure variation of s along  $\gamma(t)$ . Thus one way to solve the problem is by specifying how to transport  $E_b$  along  $\gamma(t)$ , that is, by defining **parallel transport**.

Without being too specific, to define parallel transports along a path in B we need to specify how paths in B should be lifted to a paths in E (The lifted paths are the so-called **horizontal lifts**). But this allows us to define a lifting of tangent vectors on B to tangent vectors on E. That is, we get an identification of  $T_bB$  with a subspace  $H_e$  of  $T_eE$  for any  $e \in E_b$ . The subspace  $H_e$  is a complementary summand in  $T_eE$  to the subspace of vertical vectors, that is, we get a splitting  $T_eE = V_e \oplus H_e$ .

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